#### 2007 APS USER WORKSHOP

# Overcoming insufficient oversampling ratio usi ng predetermined partial information ( Hard x-ray coherent diffraction imaging )

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**Korean Science and Engineering Foundation** 

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**Advanced Photonic Research Institute, GIST** 

User Program for Ultra-Short Quantum Beam Facility



# **Outline**

**Diffraction Imaging** 

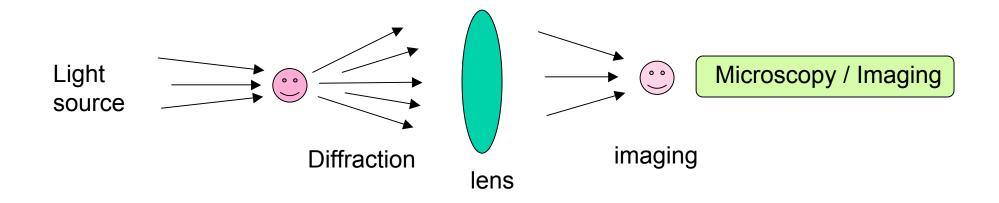
**Generalized Phase Retrieval Algorithm** 

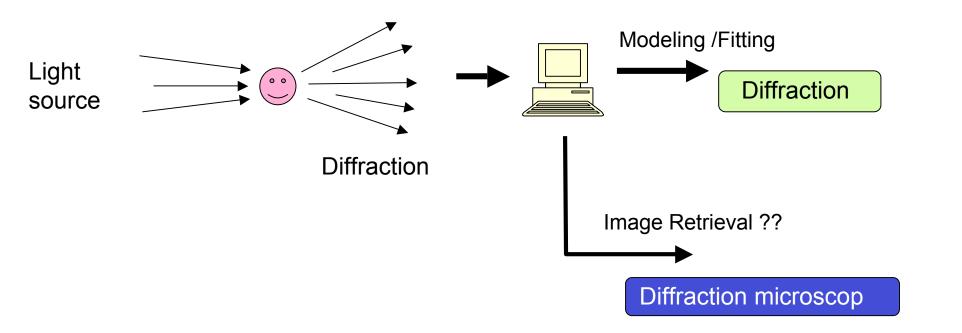
**Test: He-Ne diffraction** 

**■** Mard X-ray (7.5 KeV) Diffractive Imaging



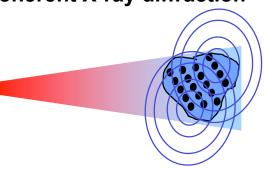
#### **Diffraction / Microscopy**





# **Coherent X-ray & Incoherent X-ray Diffraction**

#### **Incoherent X-ray diffraction**



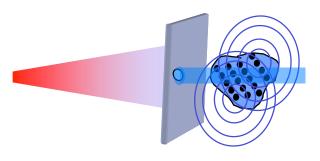
$$S(\vec{q}) = \sum_{\text{all volume}} \int_{\text{coherent volume}} \rho(\vec{r}) e^{-i\vec{q}\cdot\vec{r}} \Big|^{2}$$

$$= \left\langle \left| \int_{\text{coherent volume}} \rho(\vec{r}) e^{-i\vec{q}\cdot\vec{r}} \right|^{2} \right\rangle$$

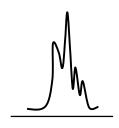
$$= \left\langle \left| \int_{\text{coherent volume}} \rho(\vec{r}) e^{-i\vec{q}\cdot\vec{r}} \right|^{2} \right\rangle$$

- ✓ Ensemble average of the Fourier transform inside the coherent volume
- ✓ Statistical average of the atomic scale structure

#### **Coherent X-ray diffraction**



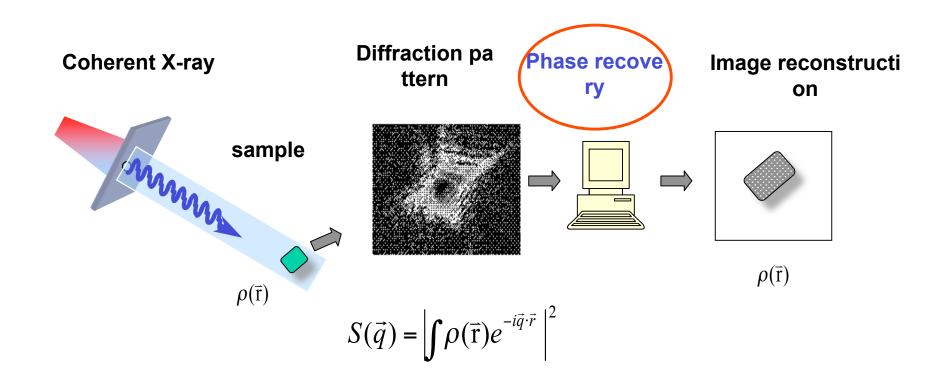
$$S(\vec{q}) = \left| \int_{\text{coherent volume}} \rho(\vec{r}) e^{-i\vec{q}\cdot\vec{r}} \right|^2$$



- ✓ Exact Fourier transform inside the coherent volume
- ✓ Individual and instantaneous structure



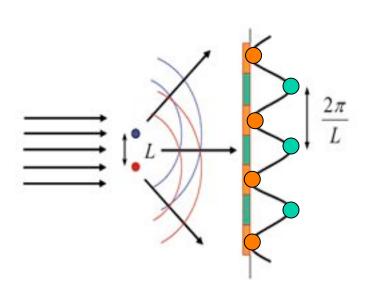
#### **Coherent x-ray diffraction microscopy**



- ✓ Nanometer scale resolution (ultimately atomic scale): single particle diffraction
- ✓ Three dimensional lensless imaging
- ✓ In-situ non-destructive imaging



#### **Phase Recovery: Oversampling**



Sampling at frequency  $2\pi/L$  is not enough to resolve interference fringes

$$|F(\mathbf{k})| = \left| \sum_{\mathbf{r}=0}^{N-1} \rho(\mathbf{r}) e^{2\pi i \mathbf{k} \cdot \mathbf{r}/N} \right|$$

$$\mathbf{k} = 0, 1, 2, \dots N-1$$

	# of unknown variables	# of independent equations
1D	2N	N
2D	2N <sup>2</sup>	$N^2$
3D	2N <sup>3</sup>	$N^3$

Minimum oversampling ratio is 2

J. Miao, P. Charalambous, J. Kirz, and D. Sayre, Nature 400, 342 (1999).



#### Oversampling Method

$$g(\mathbf{r}) = \begin{cases} \rho(\mathbf{r}) & 0 \le \mathbf{r} \le N - 1 \\ 0 & N \le \mathbf{r} \le 2N - 1 \end{cases}$$

$$|F(\mathbf{k})| = \sum_{\mathbf{r}=0}^{2N-1} g(\mathbf{r}) e^{2\pi i \mathbf{k} \cdot \mathbf{r}/(2N)}$$
 Reciprocal space amplitude constraint

#### Oversampling ratio

$$\sigma = \frac{electron\ density\ region\ +\ no-density\ region}{electron\ density\ region}$$

#### $\sigma$ > 2: the phase information exists inside the diffraction intensity!

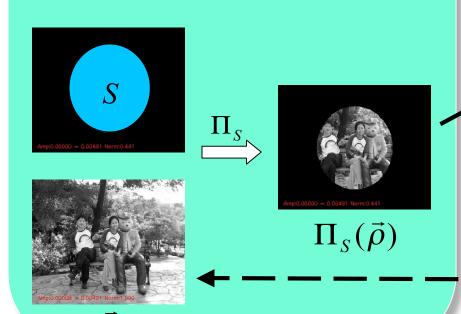
J. Miao, P. Charalambous, J. Kirz, and D. Sayre, Nature 400, 342 (1999).



#### **Elementary Projections**

#### **Support Projection**

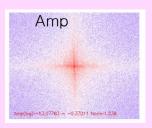
$$\Pi_{S}(\vec{\rho}) = \begin{cases} \rho_{r} & \text{for } r \in S \\ 0 & \text{otherwise} \end{cases}$$

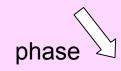


#### **Fourier Modulus Projection**

$$\Pi_F = F^{-1} \circ \widetilde{\Pi}_F \circ F$$











$$\Pi_{\scriptscriptstyle F}(ec{
ho})$$

#### **Iterative Phase Retrieval Algorithms**

$$\Pi_{S}[\rho(\vec{r})] = \begin{cases} \rho(\vec{r}) & \text{for } r \in S \\ 0 & \text{otherwise} \end{cases}$$

<HIO Algorithm>

$$\vec{\rho}_{n+1}(r) = \begin{cases} \Pi_F[\vec{\rho}_n(r)] & r \in S \\ \vec{\rho}_n(r) - \beta \cdot \Pi_F[\vec{\rho}_n(r)] & r \notin S \end{cases}$$

J.R. Fienup, Appl. Opt. 21, 2758 (1982)

<Difference Map>

$$\begin{aligned} \vec{\rho}_{n+1} &= \vec{\rho}_n + \beta \Delta \vec{\rho}_n \\ \Delta &= \Pi_S \circ [(1+\gamma_2)\Pi_F - \gamma_2] - \Pi_F \circ [(1+\gamma_1)\Pi_S - \gamma_1] \end{aligned}$$

J.R. Fienup and C.C. Wackerman, J. Opt.Soc.Am. A3,1897(1986).

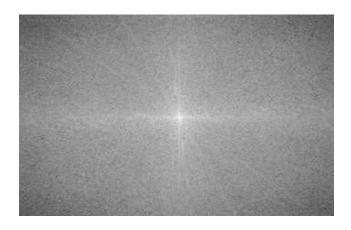
J.R. Fienup, J. Opt. Soc.Am. A4,118(1987).



# **Test of Phase Retrieval Algorithm**

2D







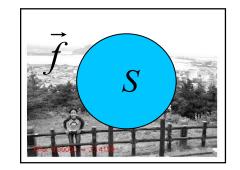


# Generalized Phase Retrieval Algorit hm



#### **Generalized Support Projection**

$$\Pi_{S(\vec{f})}(\vec{\rho}) = \begin{cases} \rho_r & \text{for } r \in S \\ f_r & \text{for } r \notin S \end{cases}$$





$$\begin{array}{c} \Pi_{S(\vec{f})} \\ \hline \end{array}$$

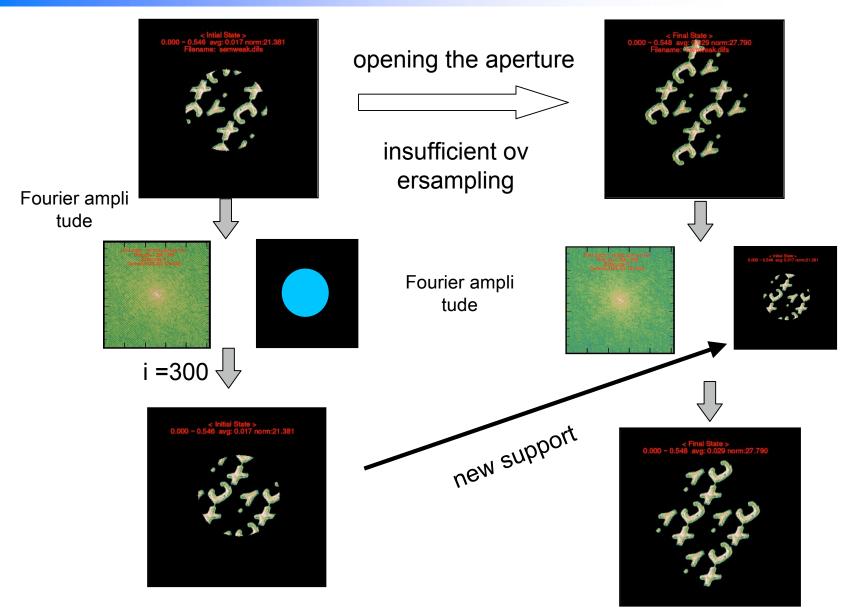


 $\vec{\rho}$ 

$$\Pi_{{ ext{S}(ec{ ext{f}}\,)}}(ec{
ho})$$



# Phase Retrieval using predetermined information





#### **Generalized Iterative Phase Retrieval Algorithms**

$$\Pi_{S}^{\vec{K}}[\rho(\vec{r})] = \begin{cases} \rho(\vec{r}) & \text{for } r \in S \\ K(\vec{r}) & \text{otherwise} \end{cases}$$

<HIO Algorithm>

$$\vec{\rho}_{n+1}(r) = \begin{cases} \Pi_F[\vec{\rho}_n(r)] & r \in S \\ \vec{\rho}_n(r) + \beta \{\vec{K}(r) - \Pi_F[\vec{\rho}_n(r)]\} & r \notin S \end{cases}$$

<Difference Map>

$$\vec{\rho}_{n+1} = \vec{\rho}_n + \beta \Delta \vec{\rho}_n$$

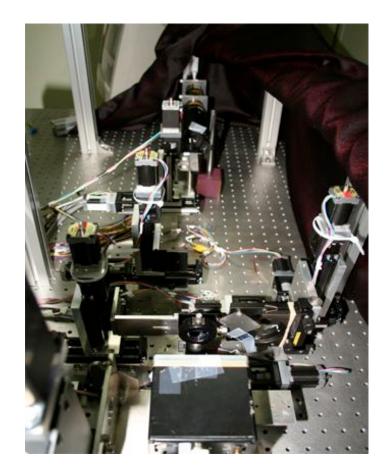
$$\Delta = \Pi_S^{\vec{K}} \circ [(1 + \gamma_2)\Pi_F - \gamma_2] - \Pi_F \circ [(1 + \gamma_1)\Pi_S^{\vec{K}} - \gamma_1]$$

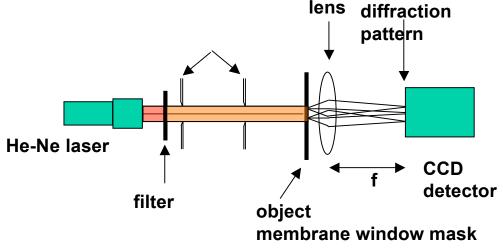


# Test of the Generalized Phase Retri eval Algorithm with He-Ne Laser Diffraction



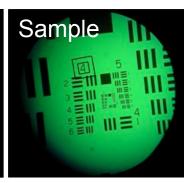
# **He-Ne Laser Experimental Setup**



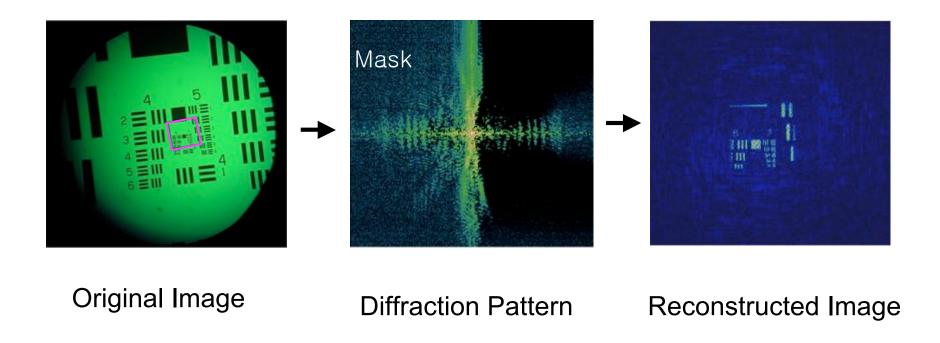






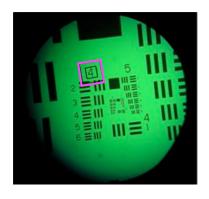


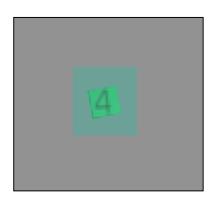
# **Typical Diffraction & Imaging**

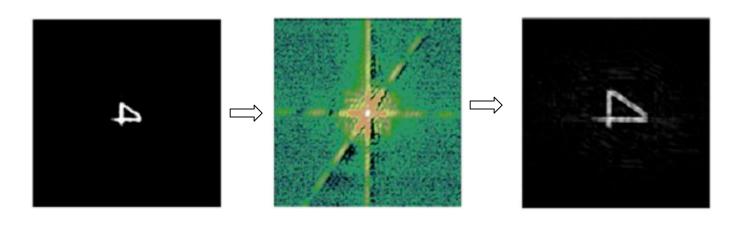




#### Reconstruction







Optical Image

Diffraction Pattern

Image reconstruction



# **Reconstruction Using Predetermined Information**

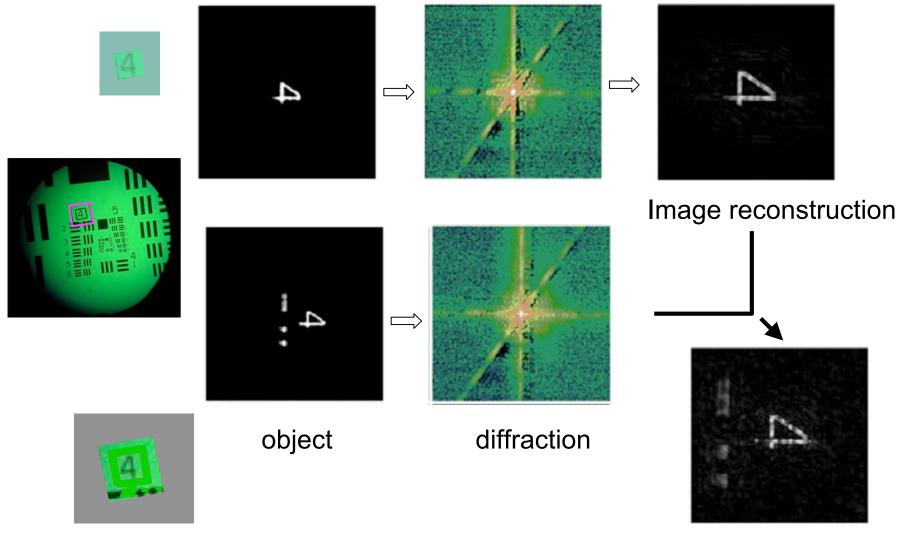




Image reconstruction with predetermined information

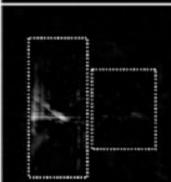
# **Dependence on Oversampling Ratio**

#### Ordinary oversampling

#### Generalized oversampling



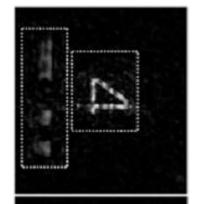
$$\sigma = 3.0$$

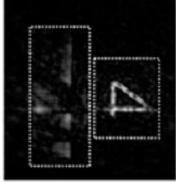


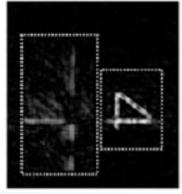
$$\sigma = 2.5$$



$$\sigma = 2.0$$







# Hard x-ray coherent diffraction imaging



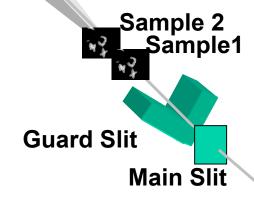
#### **Advanced Photon Source**





# **Schematic Setup (APS-8ID)**



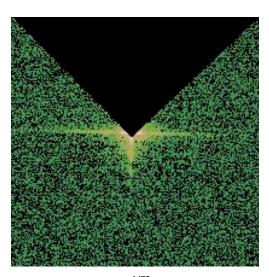


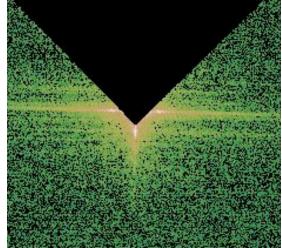
E=7.45 keV

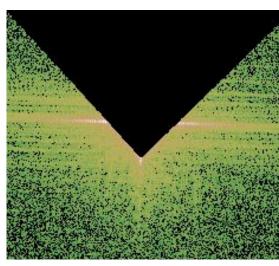
 $\lambda = 0.17 \text{ nm}$ 



#### **Central Pixels: Attenuators**







AI :360  $\mu$ m

Atten. factor: 0.0037

AI :160 HM

Atten. factor: 0.083

no attenuator

CCD Model: PI-LCX1300(Be window type)

Attenuator: Al foils for UHV purpose.

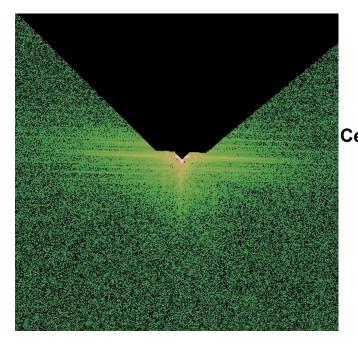
Total Expose time: 100s

(200 frames with expose time, 0.5s, were gathered safely)



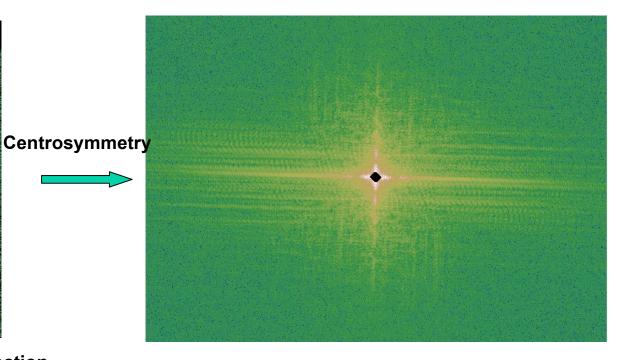
# **DATA PROCESSING**

#### Merged Data



Choose the maximum intensity direction and divide the corresponding factor

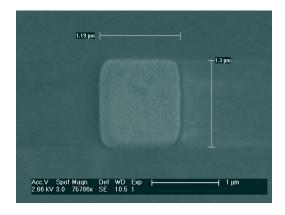
**Final Data** 

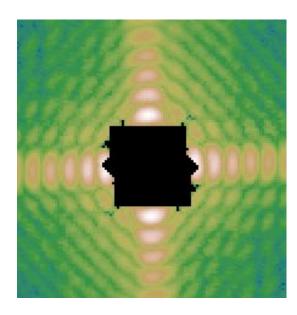


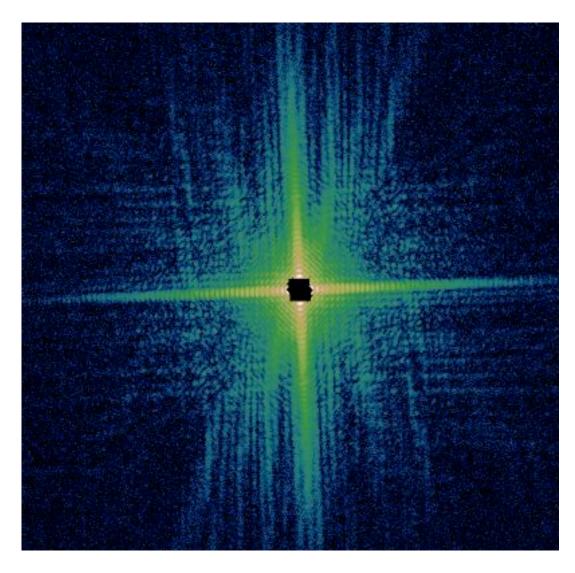
Sampling distance in real space ~ 9.3  $\mu$ m

Q range: ~ 0.061 Å -1

# **Test Pattern 1: Gold Square**

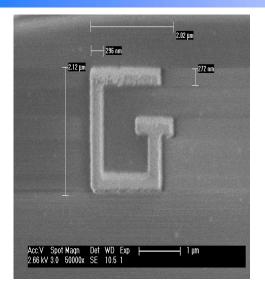


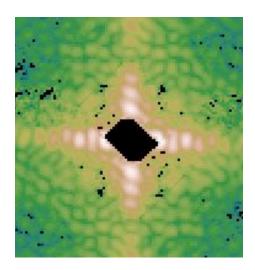


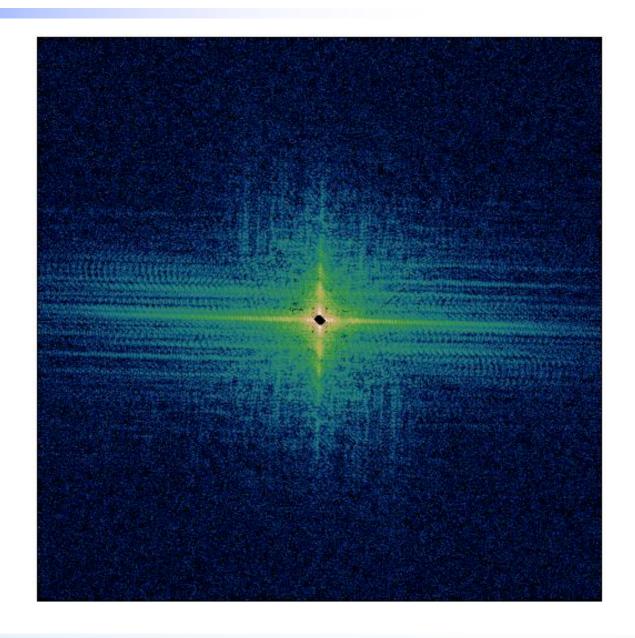




#### **Gold Letter: G**

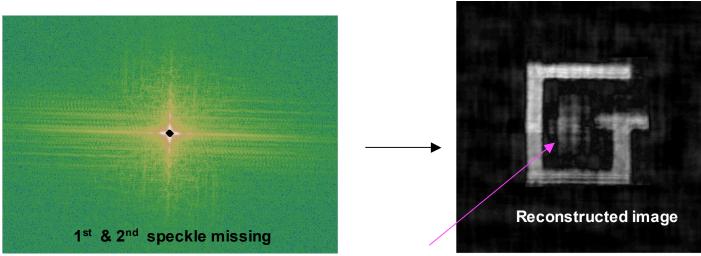








#### Image Reconstruction(HIO)

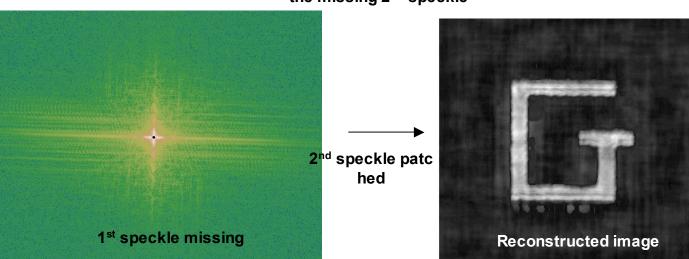


HIO Method

Iteration~ 3000

Err ~ 0.1

Artifact comes from the missing 2<sup>nd</sup> speckle



2.02 µm

2.02 µm

2.12 µm

2.12 µm

SEM Image

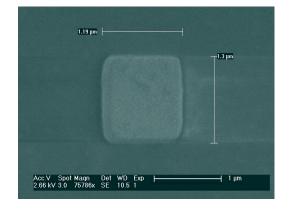
HIO Method
Iteration~ 3000

Err ~ 0.05

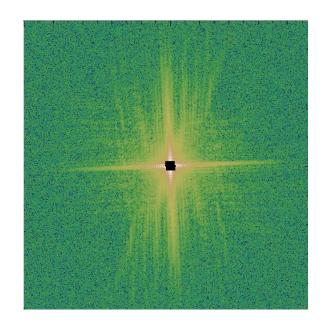
Missing data -> using Y.Nishino method (Y.Nishino et al. Phys.Rev.B 68,220101(2003)



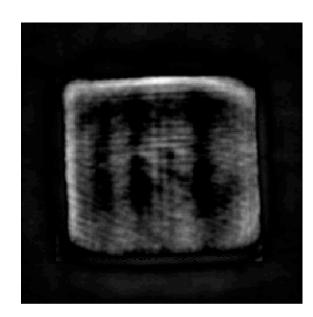
# Image Reconstruction



(SEM)



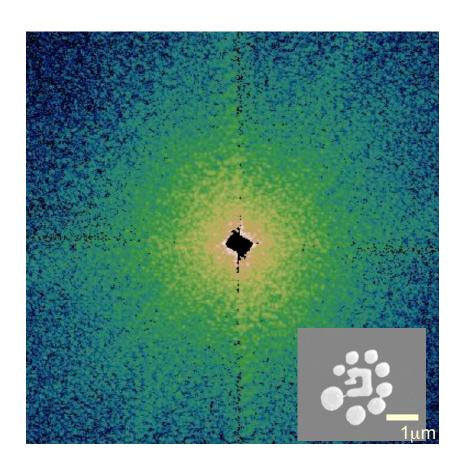


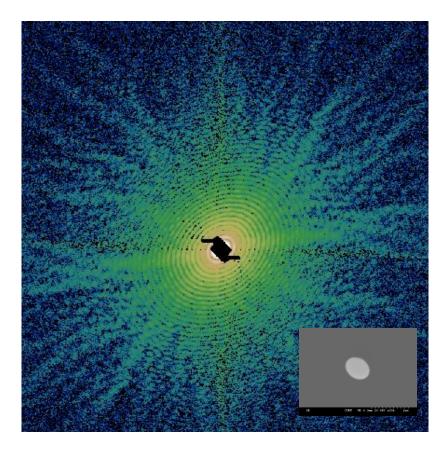


(Reconstructed)



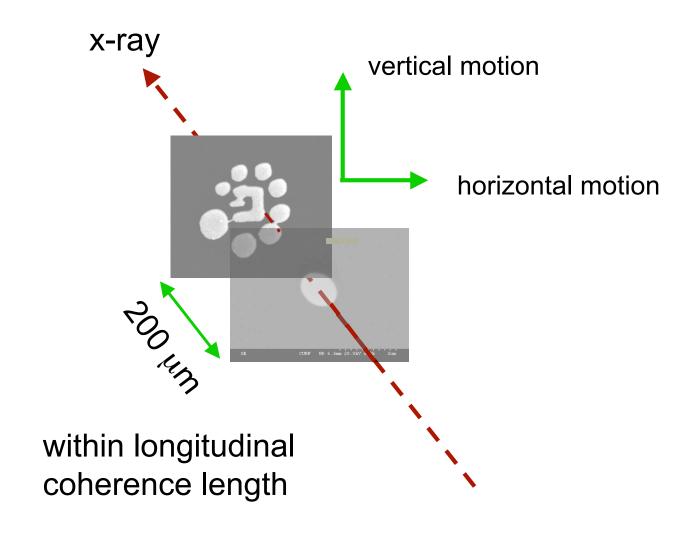
# Testing the generalized algorithm with hard x-rays





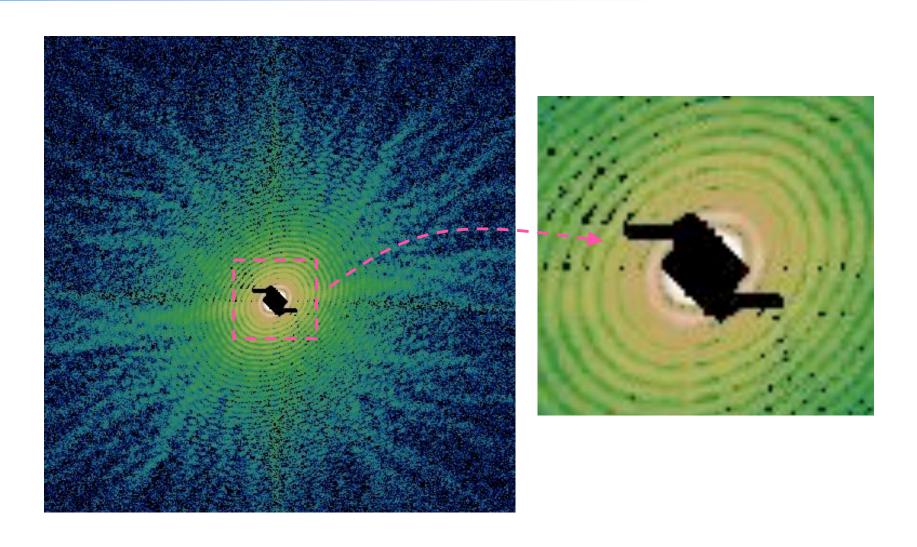


#### **Sample Geometry**



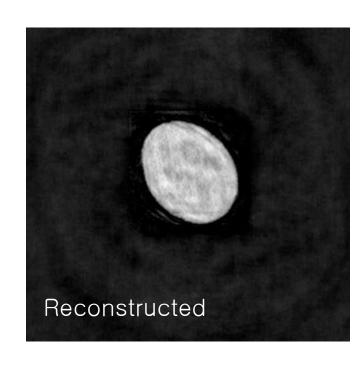


# Diffraction pattern of an ellipse

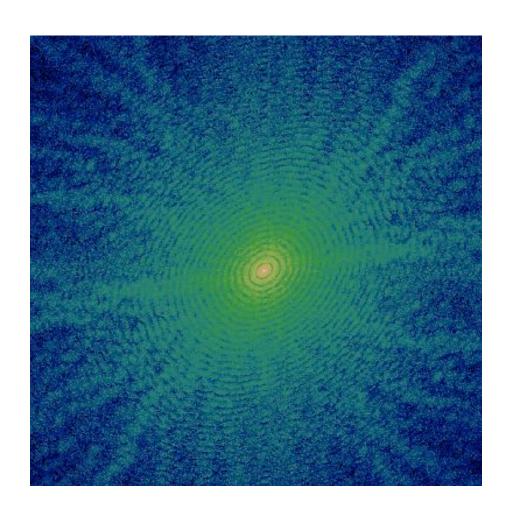




# Image Reconstruction of an ellipse



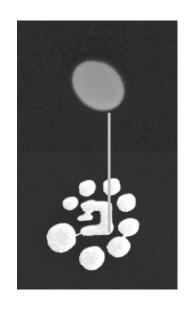
Reconstructed Image (HIO)

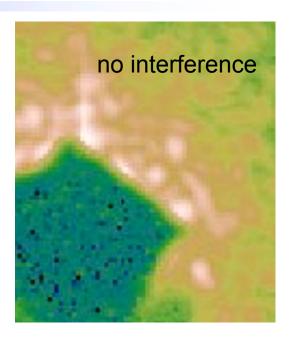


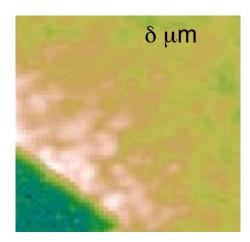
Calculated diffraction pattern

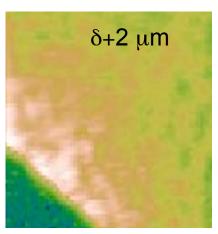


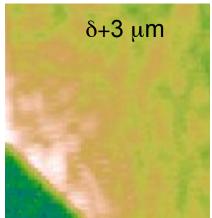
# Two particle interference pattern: Hard x-ray

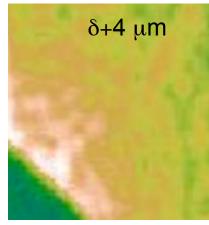




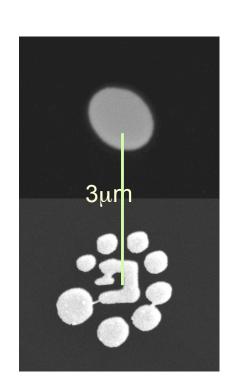


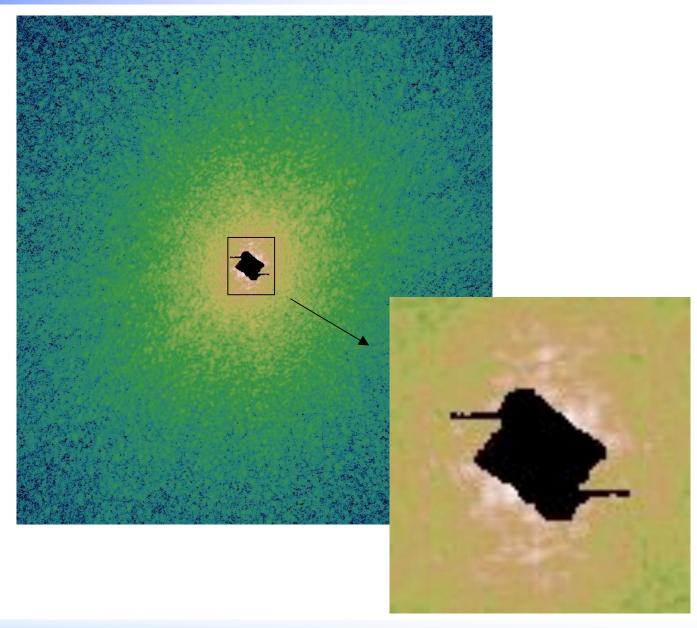






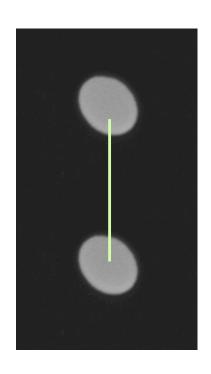
# Testing the generalized algorithm (on going)

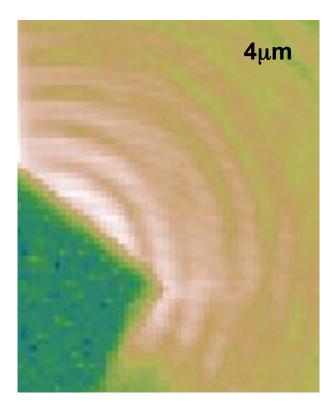


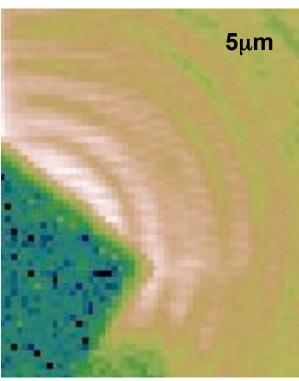




# Two ellipse interference pattern: Hard x-ray

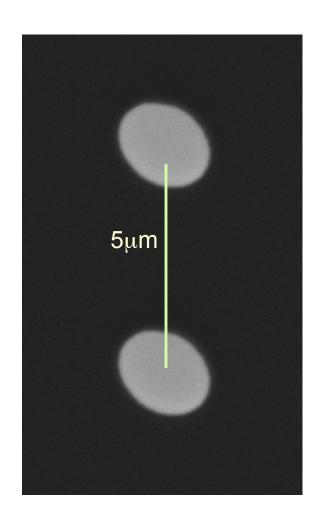


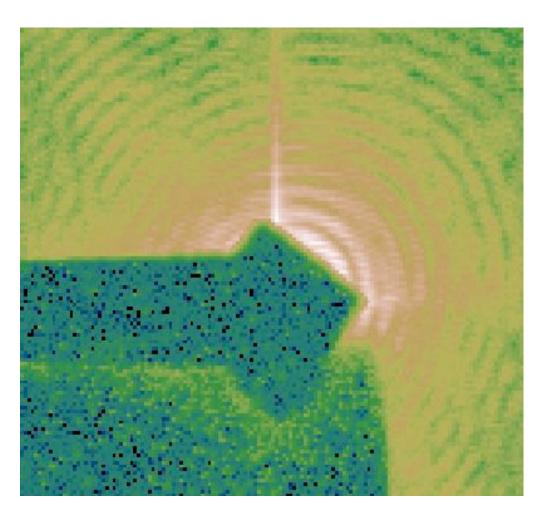






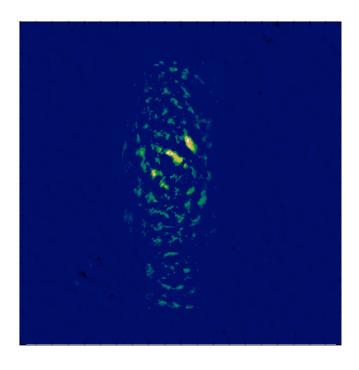
# Testing the generalized algorithm



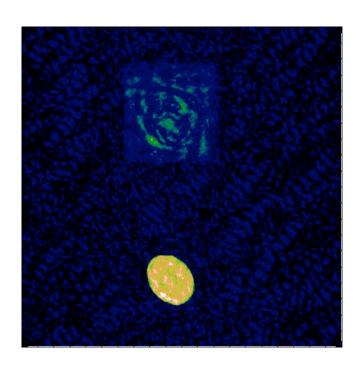




# Ordinary versus generalized algorithm



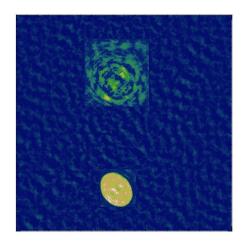
**Direct HIO** 

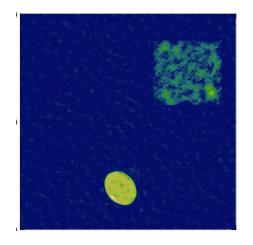


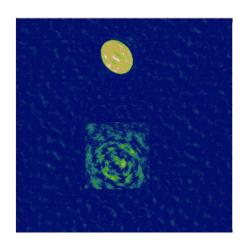
**Generalized HIO** 

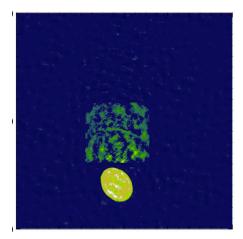


# Testing the generalized algorithm











#### Prospects of hard x-ray coherent diffraction imaging

#### Bright sides

- High resolution: wavelength of order 0.15 nm (single molecular structure often require resolution below 1 nm)
- Coherency : transverse coherence of order 10  $\mu$ m (in most cases, field of view is less than 5  $\mu$ m)
- Non vacuum applications (in-situ, in-vivo, ...)

#### Limiting factors

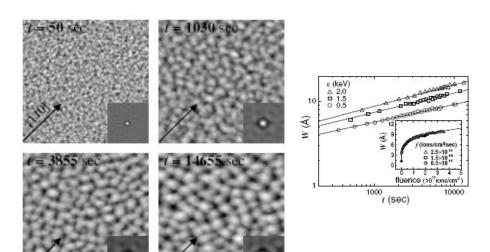
- Need higher flux x-ray sources → Future x-ray sources
- CCD detectors of large dynamic ranges are required
- Sample handling & environments (Dedicated beamlines ...)



#### Applications of hard x-ray coherent diffraction imaging

## Applications in nanotechnology (inorganic/organic)

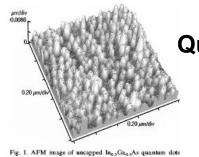
Reflection geometry is required Non-isolated specimen (x-ray pinhole) Buried Interface structure (may require sample thinning)





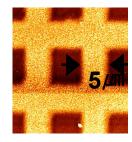
VOLUME 92, NUMBER 24

PHYSICAL REVIEW LETTERS



#### **Quantum dots**





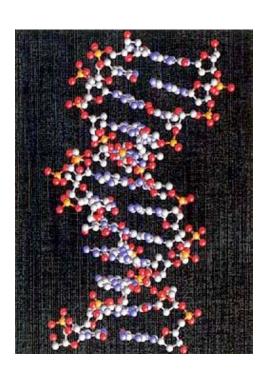
nano structures



#### Applications of hard x-ray coherent diffraction imaging

- Molecular level technology (single molecules, biology)

Sample handling (radiation damage)
Sub nanometer resolution



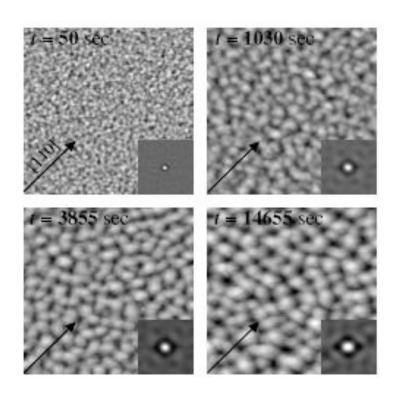
Protein crystallography
Solution small angle x-ray scattering

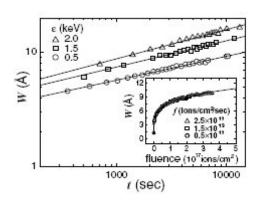
http://www.rekihaku.ac.jp/e-rekihaku/115/cover.html



# **Applications of Coherent Diffraction Imaging**

#### Nano dot formation kinetics by ion sputtering Pd (001) surface





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PHYSICAL REVIEW LETTERS



#### Quantum dot structures

#### Nano-pattern

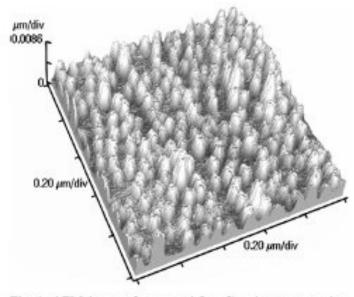
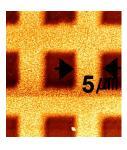


Fig. 1. AFM image of uncapped In<sub>0.5</sub>Ga<sub>0.5</sub>As quantum dots formed on GaAs(001) surface.

Physica B 336 (2003) 98-102





# **Summary**

- Developed generalized oversampling algorithm
- Verified with He-Ne laser diffraction
- Achieved hard x-ray coherent diffraction imaging

Wavelength: 0.17 nm

Resolution ~ 20 nm Field of view ~ 2  $\mu$ m

- Testing the generalized algorithm with x-ray diffraction

